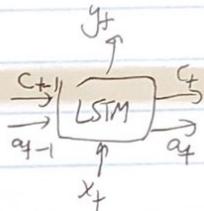


$$\begin{cases} C_t = \Gamma_u \tilde{C}_t + \Gamma_f C_{t-1} \\ \tilde{C}_t = \tanh(\Gamma_r (\Gamma_a a_{t-1}) x_t) \end{cases}$$

$$a_t = \Gamma_o C_t$$

$\Gamma_u, \Gamma_f, \Gamma_r, \Gamma_o$ "gates"
 update forget relevance adapt



$$\Gamma = \sigma(\Gamma_w x_t + \Gamma_a a_{t-1} + b)$$

GRU: $\begin{cases} \Gamma_f = 1 - \Gamma_u \\ a_t = C_t \end{cases}$ simplification!

New topic: Generative Models & Density Estimation

- Important & powerful class of ML techniques
- Generally unsupervised — learning from data, no labels
- Both aim to learn underlying $p_{\text{data}}(x)$ from samples
 - with NBS, x could be very high dimensional! (hundreds, thousands, even millions of dimensions)
- GM: given samples $x_i \sim p_{\text{data}}(x)$
 - learn to generate more samples following p_{data} .
 - general approach: take $z \sim \text{simple, known dist'n}$
e.g. $N(0, 1)^d$
 - learn map $z \xrightarrow{G} x$ | could have $d' \ll d$
s.t. $x \sim p_{\text{data}}(x)$.
↓
GM is "noised real"
 - "manifold hypothesis"
↓
data lives in \mathbb{R}^d
but secretly lives on a
sub-manifold of much lower
dimensions (data is
controlled by a much lower
dim latent space)
- DE: given samples $x_i \sim p_{\text{data}}(x)$
 - learn estimator \hat{p}_{data} for p_{data} itself
(so can report $\hat{p}_{\text{data}}(x_i)$
also know for new samples)

~~Noisy samples? Learn map?~~

- Note: GM & DG similar but can do one w/out other!
 - Can learn GM w/ p_{data} implicitly (GAN, VAE)
 - Can learn DG w/out being able to sample (KDG)

- Many poss'l applications of GM & DG!
 - countless industry applications (deepfakes, chatbots, ...)
 - in physics & astronomy
 - fast simulation: surrogate modeling ↗

↗ 
 eg: from star particles
 into stars
 - upsampling
 - simulation based inference
 ↓
 learn $p(x|\theta)$ or $p(\theta|x)$
 from samples $(x|\theta)$, perform MLE $\rightarrow \theta$
 or sample from posterior
 ↓
 powerful if x, θ very high dim! - full phase space
 beyond summary statistics
 fast if $p(x|\theta)$ slow to evaluate
 (faster than MCMC) but forward model fast to run

- phase space integration/importance sampling
 know $p(x)$ exactly but can't sample from it
 fit model for $p(x|w) \rightarrow p(x)$, sample from model
 to integrate over $p(x)$

- anomaly detection

- ($\text{low } p(x)$) - rare?

- ($\text{learn } p(x|y)$) for $y \in CR$

useful beyond
anomaly detection
of course!

interpolate y into SR

Set background model, fully data driven
for x

- - - - probably more applications out there!

4 classes of NN-based GMs:

- GANs
- VAEs
- Flows (also DE)
- Diffusion (als. ODE)

Plan is to introduce class to each one, with examples